# Variable Speed Drives





#### **Main Features**

Reference : CFW900E0242T4DB20Y2B

Product code : 15006109
Product reference : CFW900

Basic data

Rated voltage : 380 up to 480 V Input minimum-maximum voltage : 323-528 V

Number of phases:

- Input : 3 - Output : 3

Supply voltage range	380-	-480V
Overload specification	Normal Duty (ND)	Heavy Duty (HD)
Rated output current	242 A	190 A
Overload output current 60 s	266 A	285 A
Overload output current 3 s	363 A	380 A

#### Maximum applicable motor

Voltage / Frequency	Rated power (HP / kW) [1]	
voltage / Frequency	Normal Duty (ND) overload [1]	Heavy Duty (HD) overload [1]
380V / 60Hz	175 / 132	125 / 90
400V / 50Hz	175 / 132	125 / 90
440V / 60Hz	200 / 150	150 / 110
460V / 60Hz	200 / 150	150 / 110

Dynamic braking [2] : Yes

EMC filter : Yes, emissions and immunity category C3

Conducted issue: Category C3Link Inductor: YesDisconnect switch: Not applicableSafety function: STO/SS1

Electronic external power : Yes (24 Vdc ±10%)

Hardware : Standard

#### VSD power specifications

Line frequency : 50/60 Hz Line frequency range (minimum - maximum) : 48-63 Hz

Phase unbalance : Less or equal to 3% of input rated line voltage

Transient voltage and overvoltage : Category III

Three-phase input rated current:

- Three-phase input current ND : 242 A
- Three-phase input current HD : 190 A
Typical input power factor : 0.93
Displacement factor :> 0.98
Rated efficiency :≥ 98%
Efficiency class : IE2
Maximum connections (power up cycles - on/off) per hour : 60

Direct current power supply: Allow, specified input DC voltage range: 436 up to 800 Vdc

### Standard switching frequency:

- Rated switching frequency ND
- Rated switching frequency HD
- 2 kHz
- Selectable switching frequency
- 1 to 8 kHz

Memory card: MicroSD (card not included)Real-time clock: Yes, on the control boardCopy Function: Yes, by microSD card or WPS

#### Dissipated power

Invertor part	380-480V	
Inverter part	Normal Duty (ND) Heavy Duty (HD)	
Complete inverter	2620 W	2010 W
Front part of the inverter [3]	460 W	380 W

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#### VSD control specifications

#### Motor control / performance data

Control types:

- Control method - induction motor : Scalar, VVW, Vector with and without encoder

- Control type - PM motor : VVW

Control output frequency [5] : 0-250 Hz

Frequency resolution : Equivalent to 1 rpm

Encoder interface : Yes (input A/B, 24V, 32kHz)

Encoder accessory : CFW900-ENC-01: ABZ, 5-30 V, 310 kHz (not included)

Induction motor

Scalar control:

- Speed regulation : 1% of rated speed

- Speed variation : 1:20

VVW control:

- Speed regulation : 1% of rated speed

- Speed variation : 1:30

Sensorless vector control:

- Speed regulation : 0,5% of rated speed

- Speed variation : 1:100

Vector control with encoder:

- Speed regulation : 0,05% of rated speed

- Speed variation : Up to 0 rpm

Permanent magnet motor

VVW control:

- Speed regulation : 0.05% of rated speed

- Speed variation : 1:10

General control specification

Power supply available to the user:

- Output voltage : 24 Vdc ±10% - Maximum capacity [4] : 0,75 A

Backplane : CFW900-4SLOTS (Total slots for function expansion: 4).

Control modules assembled on the VSD:

- Slot A : CFW900-REL-01 - Slot X : CFW900-IOS

Inputs and outputs

Analog inputs [CFW900-IOS (Slot X) - included]

Quantity (standard) : 2

Levels : -10/0 to 10V; 0/4 to 20mA

Impedance:

- Impedance for voltage input  $\begin{array}{ll} : 400 \text{ k}\Omega \\ \text{- Impedance for current input} & : 250 \ \Omega \\ \text{Function} & : \text{Programmable} \\ \text{Maximum allowed voltage} & : \pm 30 \text{ Vcc} \\ \end{array}$ 

Digital inputs [CFW900-IOS (Slot X) - included]

Quantity (standard) : 6

Type : Configurable, NPN or PNP

Maximum low level : 5 V (DI1 to DI6)

Minimum high level : 11 V (DI1 to DI4) and 15 V (DI5/DI6)

Input current : 11 mA
Maximum input current : 13 mA

Maximum frequency : 32 kHz (DI5/6) - Not avail. V1.xx

Function : Programmable Maximum allowed voltage : 30 Vcc

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#### Saídas analógicas [CFW900-IOS (Slot X) - included]

Quantity (standard)

Levels : 0 to 10V, 0 to 20mA and 4 to 20mA

RL for voltage output :  $10 \text{ k}\Omega$  RL for current output :  $600 \Omega$  Function : Programmable

#### Relay digital outputs [CFW900-IOS (Slot X) - included]

Transistor digital output : 2 (NPN)
Maximum voltage : 24 Vdc
Maximum current : 40 mA

Maximum frequency : 32 kHz (Not avail. version V1.xx)

Function : Programmable

#### Relay outputs [accessory CFW900-REL-01 (included)]

Quantity (standard) : 2 relays NO; 1 relay NO/NC Maximum output voltage : 250 Vac / 30 Vdc, OVC III

Maximum current : 2 A

Function : Programmable

#### **Functional safety**

Safety funcions:

- Safe torque off (STO) according to IEC 61800-5-2 - Stop category 0 according to IEC 60204-1

- Safe stop 1 time controlled (SS1-t), according to IEC 61800-5-2 - Stop category 1 according to IEC 60204-1

Safety category

- SIL 3, according to IEC 61508 / IEC 62061 / IEC 61800-5-2

- PLe, category 4, according to EN ISO 13849-1

Number of inputs: 2

#### Communication

Bluetooth interface : Yes, included in HMI
USB port : Yes, available in HMI
RS-485 port : Yes, included
RS-485 protocol : Modbus RTU
Dual Ethernet port : Yes, included
Ethernet protocol 1 : Modbus TCP

Ethernet protocol 2 : Direct cloud connection (MQTT) - Embedded drive scan CAN port : Yes, with CFW900-CCAN-W accessory (not included)

CAN Protocol 1 : CANOpen
CAN Protocol 2 : DeviceNet

#### Available protections/faults

- Overcurrent/short circuit in the output
- Phase loss
- Under/Overvoltage on the DC link
- Overtemperature
- Motor overload
- Overload in the power module (IGBTs)
- External alarm/fault
- Braking resistor overload
- CPU or memory fault
- Phase-ground short circuit in the output

#### Keypad (HMI)

Availability : Included in the product

HMI installation : Local (on the inverter) or remote (via cable - not included)

Number of HMI buttons : 12

Display : Graphic LCD Indication accuracy : 5% of rated current

Speed resolution : 1 rpm

Standard HMI degree of protection : IP65 (IEC) / UL Type 12 (UL)

Remote HMI frame : Accessory

Remote HMI degree of protection : IP65 (IEC) / UL Type 12 (UL)

#### **Ambient conditions**

#### Degree of protection of VSD enclosure:

 - Front
 : IP20 (IEC) / Open-Type (UL)

 - Front with accessory
 : IP21 (IEC) / UL Type 1 (UL)

 - Rear
 : IP55 (IEC) / UL Type 12 (UL)

 Pollution degree
 : 2 (EN50178 and UL508C)

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#### Temperature:

- Minimum : -10 °C / 14 °F - Maximum (front side) : 60 °C - Maximum (back) : 45 °C

#### Current derating:

- Switching frequency of 1.5 kHz: 2%/°C from 45°C (1.1%/°F from 113°F) on the rear part.

- Switching frequency ≥ 2 kHz: 1%/°C from 40 to 45°C (0.56%/°F from 104 to 113°F) on the back and 2%/°C starting at 45°C (1.1%/°F starting at 113°F) on the rear part.

#### Relative humidity (non-condensing)

- Minimum : 5% - Maximum : 90%

#### Altitude

- Rated conditions : 1000 m (3281 ft)
- Maximum allowed for operation (with derating factor) : 4000 m (13123 ft)

#### Current and voltage deratings as a function of altitude:

- Current derating factor (for altitudes above rated) : 1% for each 100 m above (0,3% for each 100 ft above) - Voltage derating factor (for altitudes above 2000 m / 6562 ft) : 1,1% for each 100 m above (0,33% for each 100 ft above)

#### **Sustainability Directives**

RoHS : Yes

Conformal Coating : 3C2 (IEC 60721-3-3:2002)

#### Frame size, dimensions and weight

Size : E

 Height
 : 675 mm / 26.6 in

 Width
 : 335 mm / 13.2 in

 Depth
 : 358 mm / 14.1 in

 Weight
 : 63.5 kg / 140 lb

#### **Mechanical installation**

Mounting position : Surface or flange

Fixing screw : M8

Tightening torque : 20 N.m / 14.76 lb.ft

Allows side-by-side assembly : Yes, IP20 degree of protection - Top : 150 mm / 5.91 in

- Top : 150 mm / 5.91 in
- Bottom : 250 mm / 9.84 in
- Front : 20 mm / 0.78 in
- Between inverters (IP20) : 0 mm / 0 in
- Between inverters (IP21 or UL Type 1) : 30 mm / 1.18 in

Allows horizontal mounting : No

#### **Electrical connections**

	Recommended cable	Recommended tightening torque
	gauge @ 75 °C (167 °F)	
Power supply and motor	2x 70 mm² (2x 1/0 AWG) ND 30 N.m / 22.1 lb.ft	
	120 / 2x35mm² (4/0 / 2x1AWG)HD	
Braking	2x 50 mm² (2x 1 AWG)	30 N.m / 22.1 lb.ft
Grounding	95,0 mm² (3/0 AWG)	15 N.m / 11.1 lb.ft
Control	XC1/XC2: 0.2-1.5mm² (24-16AWG)	Spring push-in connection
	XC30: 0.2-2.5mm <sup>2</sup> (24-12AWG)	

#### **Additional specifications**

 $\begin{array}{ll} \text{Maximum breaking current} & : 400 \text{ A} \\ \text{Minimum resistance for the brake resistor} & : 2 \ \Omega \end{array}$ 

Recommended aR fuse [6] : FNH2-400K-A
Recommended aR fuse [6] : Not applicable
Recommended circuit breaker [6] : ACW630H-ETS630-3
Recommended circuit breaker [6] : UBW600H-FTU600-3A

HMI battery type : CR2032 HMI battery life expectancy : 10 years

#### Power loss data according to Ecodesign Directive 2019/1781 (IEC 61800-9 standard)

Rated supply voltage : 400 V
Rated output current : 242 A
Motor power : 132 kW
Switching frequency : 2 kHz

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Aparent power of the inverter (Sr,equ)

: 167.7 kVA

VSD (CDM) power losses at the following operating points (speed, torque) [7]:

	Torque: 25%	Torque: 50%	Torque: 100%
Speed: 0%	0.5%	0.7%	1.1%
Speed: 50%	0.6%	0.8%	1.3%
Speed: 90%		0.9%	1.5%

Standby power losses: 66 W / 0.1%

Efficiency class : IE2

#### Standards

Standards	
Safety standards	<ul> <li>- UL61800-5-1 - Adjustable Speed Electricla Power Drive Systems - Part 5-1: Safety Requirements - Electrical, Thermal and Energy</li> <li>- EN 61800-5-1 - Safety requirements electrical, thermal and energy</li> <li>- EN 50178 - Electronic equipment for use in power instalations</li> <li>- EN 60146 (IEC 146) - Semiconductor converters</li> </ul>
Specifications standard	<ul> <li>EN 61800-2 - Adjustable speed electrical power drive systems - Part 2: General requirements - Rating especifications for low voltage adjustable frequency AC power drive systems</li> </ul>
Electromagnetic Compatibility (EMC) standards	- EN 61800-3 - Adjustable speed electrical power drive systems - Part 3: EMC product standard including specific test methods - EN 55011 - Limits and methods of measurement of radio disturbance characteristics of industrial, scientific and medical (ISM) radio-frequency equipment - CISPR 11 - Industrial, scientific and medical (ISM) radio-frequency equipment - Eletromagnetic disturbance characteristics - Limits and methods of measurement - EN 61000-4-2 - Eletromagnetic compatibility (EMC) - Part 4: Testing and measurement techniques - Section 2: Eletrostatic discharge immunity test - EN 61000-4-3 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 3: Radiated, radio-frequency electromagnetic field immunity test - EN 61000-4-4 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 4: Electrical fast transient/ burst immunity test - EN 61000-4-5 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 5: Surge immunity test - EN 61000-4-6 - Eletromagnetic compatibility (EMC) - Part4: Testing and measurement techniques - Section 6: Immunity to conducted disturbances, induced by radio-frequency fields - EN 61000-4-11 - Testing and measurement techniques - Voltage dips, short interruptions and voltage variations immunity tests
Mechanical construction standards	- EN 60529 - Degrees of protection provided by enclosures (IP code - UL 50 - Enclosures for electrical equipment
Ecodesign standards	<ul> <li>IEC 61800-9 Parts 1&amp;2 - Adjustable speed electrical power drive systems - Ecodesign for power drive systems, motor starters, power electronics and their driven applications</li> </ul>
Functional safety standards	- EN 61800-5-2 - Adjustable speed electrical power drive systems - Part 5-2: Safety requirements - Functional - EN ISO 13849-1 - Safety of machinery - Safety-related parts of control systems - Part 1: General principles for design - EN 62061 - Safety of machinery - Functional safety of safety-related control systems - IEC 61508 Parts 1-7 - Functional safety of electrical/electronic/programmable electronic safety-related systems - EN 60204-1 - Safety of machinery - Electrical equipment of machines - Part 1: General requirements

#### Notes

- 1) Orientative motor power, valid for WEG Motors standard of IV poles. The correct sizing must be done according to the rated current of the used motor, which must be equal or lower than the rated output current of the VSD.
- 2) Braking resistor is not included.
- 3) When VSD is flange mounted, that power losses data refer to the power losses of the front part of the VSD that is inside the cabinet (the rest of the VSD losses are outside the cabinet).
- 4) That power supply is also used to feed the control modules (accessories). Information on correct sizing is provided in CFW900 User's Manual.
- 5) Typical maximum value considering the switching frequency settings as per factory default (it is possible to increase the maximum output frequency that can be generated by the VSD by increasing the switching frequency). Maximum possible value: switching frequency 10.
- 6) There are variations to meet UL and CE standards. For further information refer to CFW900 User's Manual.
- 7) VSD power losses in relation to its rated apparent power (Sr,equ).

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8) All images are merely illustrative. 9) For further information refer to CFW900 User's Manual.	